Autonics

Multi-Channel Modular Type High Performance Temperature Controller [Control Module] TMH2/TMH4 Series

INSTRUCTION MANUAL





Thank you for choosing our Autonics product. Please read the following safety considerations before use.

■ Safety Considerations

**Please observe all safety considerations for safe and proper product operation to avoid hazards.

★★ symbol represents caution due to special circumstances in which hazards may occur.

⚠Warning Failure to follow these instructions may result in serious injury or death. ▲Caution Failure to follow these instructions may result in personal injury or product damage

1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, fire, or economic loss

- 2. Install on a device panel to use. Failure to follow this instruction may result in fire.
- 3. Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire.
- 4. Check 'Connections' before wiring.
- Failure to follow this instruction may result in fire
- 5. Do not disassemble or modify the unit.
- Failure to follow this instruction may result in fire.

 Caution

1. When connecting the power input and relay output, use AWG 20 (0.50mm²) cable or over and tighten the terminal screw with a tightening torque of 0.74 to 0.90Nm.

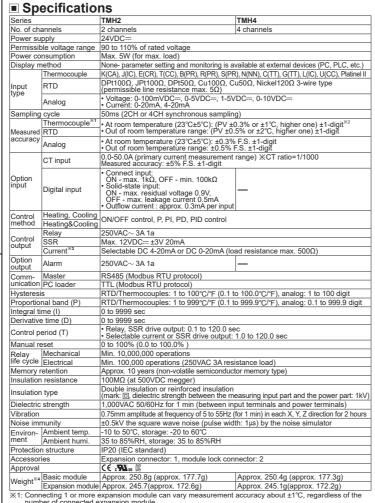
When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to

16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90Nm. Failure to follow this instruction may result in fire or malfunction due to contact failure.

2. Use the unit within the rated specifications.

- Failure to follow this instruction may result in fire or product damage 3. Use dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire.
- 4. Do not use the unit in the place where flammable/explosive/co rosive gas, humidity, direct sunlight
- Failure to follow this instruction may result in explosion or fire
- 5. Keep metal chip, dust, and wire residue from flowing into the unit. Failure to follow this instruction may result in fire or product damage.
- Ordering Information

X1: Since the expansion module is not supplied with TMH 2 - 4 2 R B Basic module Expansion module Control output Relay output SSR drive output Selectable current or SSR drive output CT input, digital input (DI-1/2), alarm output 1/2, RS485 comm. output Input/Output option CT input, digital input (DI-1/2), arm output 1/2/3/4, RS485 comm. output 4 channels Advanced Multi-Channel Modular Temperature Controlle

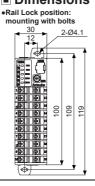


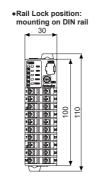
Thermocouple K, J, N, E below -100°C, L, U, PLII and RTD Cu50Ω, DPt50Ω

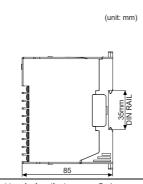
 (PV ±0.3% or ±2°C, Injder one) ±1-digit

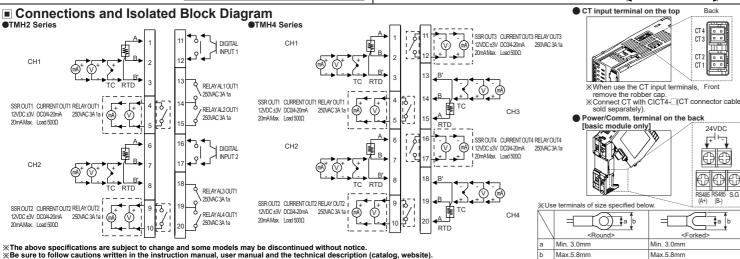
 Thermocouple C, G and R, S below 200°C; (PV ±0.3% or ±3°C, higher one) ±1-digit
 Thermocouple B below 400°C; there is no accuracy standards.
 Out of room temperature range
 RTD Cu50Ω, DPt50Ω: (PV ±0.5% or ±3°C, higher one) ±1-digit
 Thermocouple R, S, B, C, G; (PV ±0.5% or ±5°C, higher one) ±1-digit
 Thermocouple R, S, B, C, G; (PV ±0.5% or ±5°C, higher one) ±1-digit
 Thermocouple R is set to current output, the heater current value monitoring function through the CT input terminal of the control module is not available.
 The weight includes packaging. The weight in parenthesis is for unit only.
 Environment resistance is rated at no freezing or condensation.

Dimensions

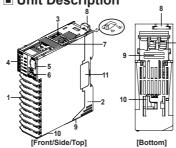








Unit Description



[basic module only]
Supplies power to both basic control/expansio module and communicates with one or more 3. CT input termina When using the CT input terminal,

2. Power/Comm. terminal

Input/Output terminal
 For specific information about terminal formation, please refer to '
 Connections and Isolated Block

remove the rubber cap and connect CT in the same direction with right Connect CT with CICT4
Connect CT with CICT4
(CT connector cable, sold separately).

When connecting CT connector and

CT input terminal,

align the concever part (M) and the co

Front

4. Indi ●TMH					align the concave part (凹) and the convex part (凸).					
Indica	ator	_	Status	power ON ^{*1}	Control output	Auto tuning ^{*2}		tput nally Open) ON (CLOSE)		
PWR CH 1	AL1	LED 1	PWR (green)*3 CH1 (red) CH2 (red) (red) (red)	_	ON ON ON ON ^{×4} ON ^{×5}	ON Flash Flash OFF	_			
	AL2 AL3 AL4	LED 2	(yellow) AL1 (yellow) AL2 (yellow) AL3 (yellow) AL4 (yellow)	Flash (4,800bps) Flash (9,600bps) Flash (19,200bps) Flash (38,400bps) Flash (115,200bps)	Module c	omm. stat	OFF OFF OFF	ON ON ON	OFF OFF OFF	ON ON ON

TMH4 Series									
Indica	tor	_	Status	Initial power ON ^{*1}	Control output	Auto tuning ^{**2}			
LED 1	LED 2	LED 1	PWR (green)**3		ON	ON			
	\Box		CH1 (red)		ON	Flash			
PWR			CH2 (red)	l —	ON	Flash			
CH 1			CH3 (red)		ON	Flash			
CHI			CH4 (red)		ON	Flash			
CH 2			(yellow)	Flash (4,800bps)	Module comm.	status ^{×6}			
			(yellow)	Flash (9,600bps)		_			
CH 3		LED 2	(yellow)	Flash (19,200bps)	_	_			
	\Box		(yellow)	Flash (38,400bps)	_	_			
CH 4			(yellow)	Flash (115,200bps)	 	_			

- #1: At the moment when power is on, the indicator of set communication speed flashes for 5 sec.

 #2: Indicator of the channel, which is in the process of auto-tuning, flashes at 1 sec interval.

 #3: When communicating with external device, PWR indicator flashes.

 #4: Turns on, when CH1 outputs cooling control in the heating&cooling control method.

 #5: Turns on, when CH2 outputs cooling control in the heating&cooling control method.

 #6: Displays communication status in control output, auto-tuning or operating RUN mode.

 ON: normal / flash: abnormal / OFF: not communicating

 5. PC loader port: PC loader port supports serial communication between single module and PC.

 It needs EXT-US (converter cable)+SCM-US (USB/Serial converter, sold separately) for communicating.

 6. Communication address setting switch (SW1): Set the communication address.

 If changing the communication address by setting switch, use the flat head driver which is 2mm size or plastic driver. If not, it may cause product damage.
- driver. If not, it may cause product damage.

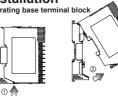
 7. Communication address group switch (SW2): When setting the communication address over 16, select +16.

 8. Rail lock. Rail lock helps installing the device to DIN rail or with bolts.

 9. Lock lever: Lock lever holds module body and base tightly.

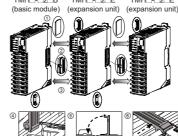
 10. Module lock connecter hole: When connect modules, insert module lock connector in the hole in order to enhance coherence between modules.
- 11. END cover: When connect modules, remove END cover in order to connect expansion connector

Installation



Pull the body of the module and open up. wWhen connecting base terminal block, align the upper concave part (凹) of the body and the upper convex part (凸) of the base. If the upper parts are not align correctly, it may damage to the inner connector

TMHI-12 E

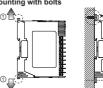


Insert expansion connector.Put all together tightly (max. 31 units). 1) Insert module lock connector. ©Push module lock connector and insert in lock connector hole of another module on the side.

(a) Push module lock connector to the lock direction Supply adequate power for power input specifications and overall capacity

(Max. power when connecting 32 modules



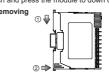


 Pull the rail lock at the top and bottom of the module Insert bolts and fix it on rail lock (fixing torque is 0.5 to 0.9N·m.)

4. Mounting on DIN rail 4.4.1 Installing



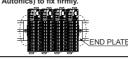
②Push and press the module to down direction



Press the module down ②Pull the module body forward. XInstall the module vertically.



XUse end plates (sold separately, not available nics) to fix firmly



■ Communication Setting

It is for parameter setting and monitoring via ex

 Interface 4800, 9600 (default), 19200, 38400, 115200 bps Connection type RS485 EIA RS485 Compliance with 1-bit (fixed) Start bit standard 32 units (address: 01 to 32) (in case connecting TMHC module 16 units (address: 01 to 16)) Synchronous method Asynchronous
Comm. method Two-wire half duplex None (default), Odd, Even 1-bit, 2-bit (default) Comm. effective range Max. 800m

Application of system organization

XOnly for RS485 communication output model. RS232C/ B (-) RS485 DEVICE 0 A(+)B(-) A(+)B(-) A(+)B(-) A (+) #31 RS485 DEVICE #2 DEVICE

(It is recommended to use Autonics communication converter, SCM-WF48 (Wi-Fi to RS485-USB wireless communication converter, sold separately), SCM-US481 (USB to RS485 converter, sold separately), SCM-US481 (USB to Serial converter, sold separately), SCM-US6 (USB to Serial converter, sold separately). Please use twisted pair wire, which is suitable for RS485 communication, for SCM-WF48, SCM-US481 and SCM-381.

Set the communication address setting

Set the communication address with the communication address setting switch (SW1) and communication address group switch (SW2) (default: [SW1] 1, [SW2] +0).

SW1		Ø														
SW2	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
+0 +16	16	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
+0 +16	32	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
O																

Caution for communication address setting
 After changing communication address via the power/comm. terminal, reboot the device.

Comprehensive Device Management Program[DAQMaster]

processes. DAQINIASIEI CAIT DE GOWINDAGEG ITOTT OUT WEDSILE AT WWW.AUTOTICS.COTT.						
Minimum specifications						
IBM PC compatible computer with Pentium III or above						
Windows 98/NT/XP/Vista/7/8/10						
256MB+						
rd disk 1GB+ of available hard disk space						
Resolution: 1024×768 or higher						
RS232C serial port (9-pin), USB port						

Error Display

ı											
l	Indicator Status	Input error ^{*1}	Remote SV error ^{*2}								
1	PRW	ON (red)	ON (green)								
ı	CH□ ^{×3}	Flash (red)	Flash (red)								

X1: Input error: input value is below the input range (LLLL) / input value exceeds input range (HHHH) / input sensor wire is down or input sensor is disconnected (OPEN).

 X2: Remote SV error: communication error of Remote SV master and internal communication / input of master channel is LLLL/HHHH/OPEN when the channel is subjected to display PV.

 X3: An indicator of relative channel flashes.

 After main cause of the error is solved, error status is cleared and the device is returned to the normal operation automatically

Manuals

For the detail information and instructions, please refer to user manual and user manual for communication, and be sure to follow cautions written in the technical description (catalog, website). Visit our website (www.autonics.com) to download manuals.

Cautions during Use

. Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents

Check the polarity of the terminals before wiring the temperature sensor.

For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire. 3. Keep away from high voltage lines or power lines to prevent inductive noise.

In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

Do not use near the equipment which generates strong magnetic force or high frequency noise.

4. Do not apply excessive power when connecting or disconnecting the connectors of the product.

5. Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.

Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
 When changing the input sensor, turn off the power first before changing.

After changing the input sensor, modify the value of the corresponding parameter

Power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
 Do not overlapping communication line and power line.
 Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect

of external noise.

For accurate temperature measurement, warm up the unit over 20 min after turning on the power. 11. Mounting multiple devices in any way other than the specified mounting method may cause heat to build up inside, which will shorten their service life. If there is a possibility of the ambient temperature rising to a temperature above the specified temperature range, take steps, such as installing fans, to cool the device Be sure that the cooling method in not cooling just the terminal block. If only the terminal block is cooled, measurement errors may occur.

12. Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.

- Do not wire to terminals which are not used.
 Install DIN rail vertically from the ground.
- 15. This unit may be used in the following environments ment condition rated in 'Specifications') ②Altitude max. 2,000m ③Pollution degree 2

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